



**CALIFORNIA STATE SCIENCE FAIR
2017 PROJECT SUMMARY**

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| Name(s) Jacob S. Kisow | Project Number S0308 |
| Project Title Versatility of 3D Printed Exoskeleton Hand | |
| Abstract Objectives/Goals The purpose of my project is to prove the usefulness and versatility of 3D printing in the world of prosthetics and overall medical usefulness of 3D printing. This project in particular is designed to help patients with various neuromuscular diseases gain extra strength to help perform everyday tasks that may be difficult for them. Methods/Materials PROCEDURES: Model exoskeleton prototype in CAD software Print prototype using 3D printing Assemble and test prototype Redesign any components necessary. MATERIALS: CAD Software & computer 3D Printer & filament Solenoid Battery Box Wiring Microswitch Velcro Results My experiment was somewhat successful in that it proved 3D printing can be a budget-minded option for quick, personalized medical needs. Conclusions/Discussion Overall, my project was a great proof-of-concept. The project was easily affordable coming in at under \$30, however, the motors did not reach the necessary power to have a significant effect on one's hand strength. In the future, I would worry less about a budget and more about a strong assistant. | |
| Summary Statement My project is about showing the versatility of 3D printing in the medical field, my project specifically is designed to give strength to patients with neuromuscular diseases. | |
| Help Received None. All prototypes were designed, printed, assembled, and tested in my bedroom and garage. | |